

June 1, 2016

Luis A. Vega, Ph.D. Manager National Marine Renewable Energy Center University of Hawaii 1680 East West Road, POST 112A Honolulu, HI 96822

Subject: May 2016 Monthly Report – RCUH P.O. #Z10115098

Dear Luis,

The following constitutes my monthly report for the subject agreement for services associated with May 2016.

Work Completed under Activity 1: "Provide technical and software support services to HNEI technical staff in programming data acquisition (DAS) controllers and analyzing data records in the following areas as assigned":

- Monitored the device regularly via remote connection to the NWEI host PC in Room 106, Battery French. Downloaded data from PC as necessary, and updated device control settings when necessary.
- Analyzed power data to produce monthly power performance data plots; see Attachment 1 for results.
- Analyzed Azura float angle data using MATLAB to produce a plot of 30 minute average float angle data for the deployment period. The data shows that in mid-May, the second Azura float angle sensor failed (another redundant sensor failed in April). Prior to the failure, the data shows that hull ballast had continued to be stable since the beginning of 2016. See Attachment 2 for these results.
- Plotted daily humidity sensor data for the cRIO controller enclosure and drybox on board the Azura. The drybox, which is entirely sealed from the Azura hull, has a slowly increasing humidity that is now 10%. The humidity inside the cRIO enclosure also continues to slowly increase, and is now at 30%. See Attachment 3 for a plots of these results.
- Uploaded monthly data to DOE repository through end of April.

Please let me know if you have any questions or comments concerning this project.

Sincerely,

Terry Lettenmaier

Attachment 1: Azura power performance data plots

- Attachment 2: Azura 30 minute average float angle data plots
- Attachment 3: Azura cRIO enclosure and drybox humidity

Attachment 1

Azura power performance data plots



Summary

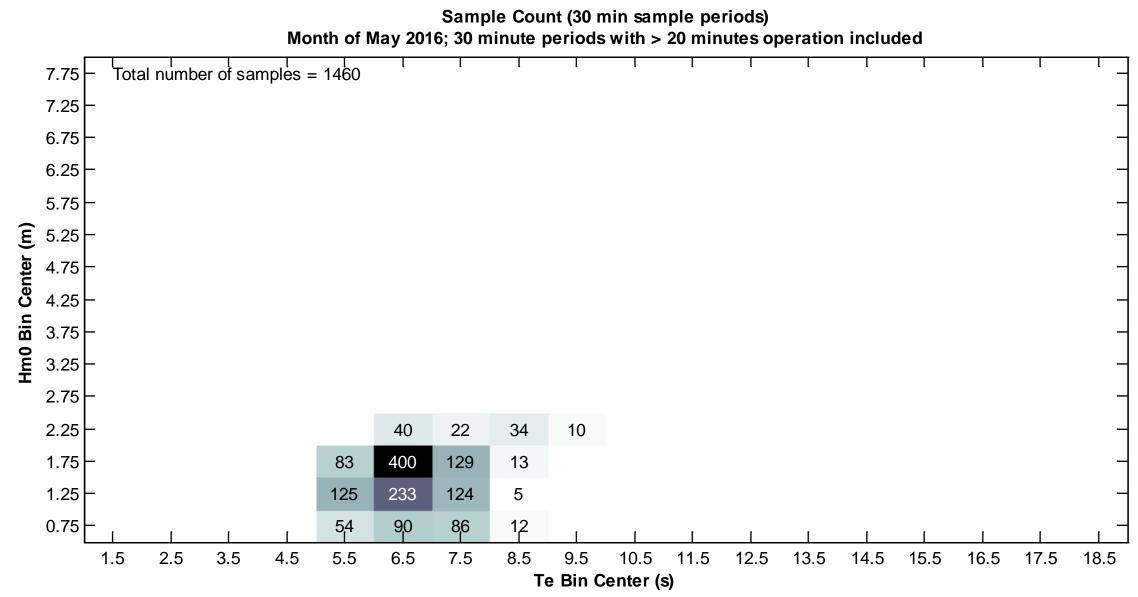
- Azura power performance was calculated and is presented as described in IEC Technical Specification 62600-100.
- Device performance is presented per IEC 62600-100 using capture length and normalized power matrices. Normalized
 power was calculated from capture length and energy flux of representative spectra for each H_{m0}-T_e bin.
- Average power matrices, 95th percentile power matrices, and percent difference between normalized power and average power are also presented.
- The representative spectra for IEC 62600-100 calculations were calculated by taking the average of all spectra recorded for each bin, then shifting the magnitude and frequency of the average spectra so that their H_{m0} and T_e are at the center of each bin.
- Plots of May 2016 data only are shown on Slides 3-11
- Plots of cumulative data for the entire deployment period January-May 2016 are shown on Slides 13-21
- Azura was operated (output connected to grid) for 733 hours in May (98.6% of month). Most of the down time was during temporary shut downs until the device controller was manually reset after brief grid voltage interruptions.
- Device control was continued through all of May in constant hydraulic motor displacement mode, with the settings cycled between six different settings. This is the simplest control method possible for the Azura.



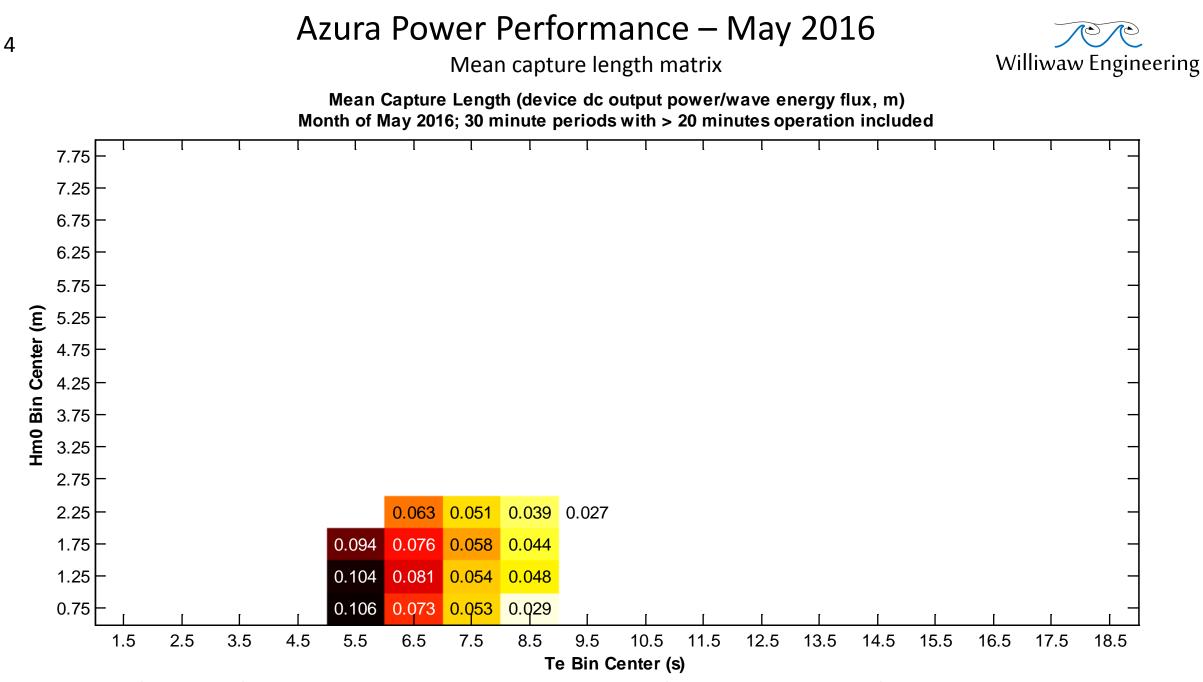
Azura Power Performance Monthly Data May 2016

Data samples collected





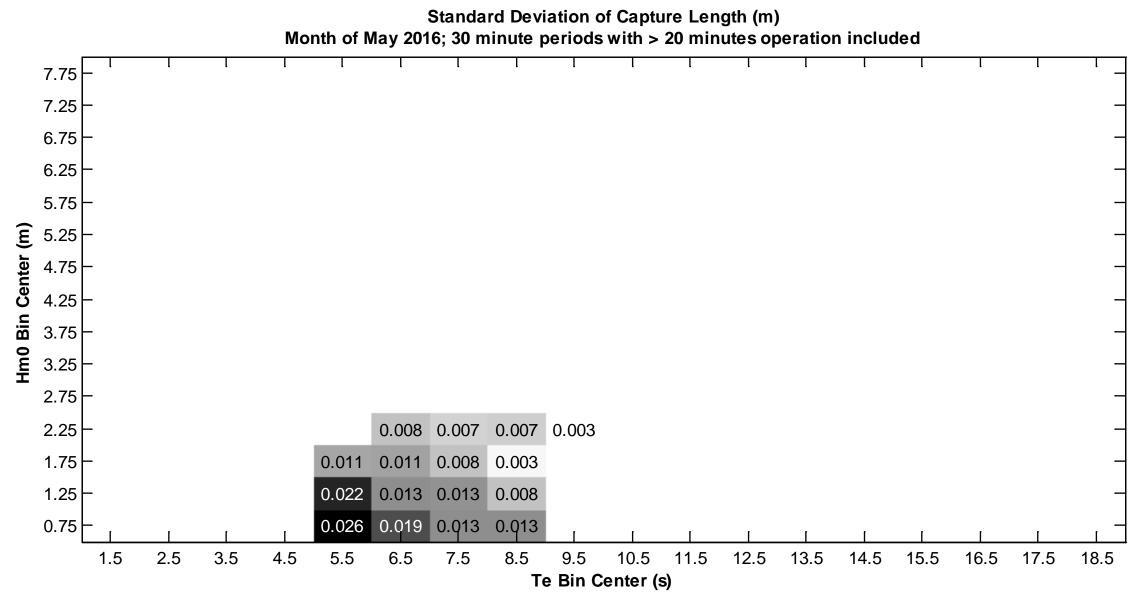
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Standard deviation of capture length

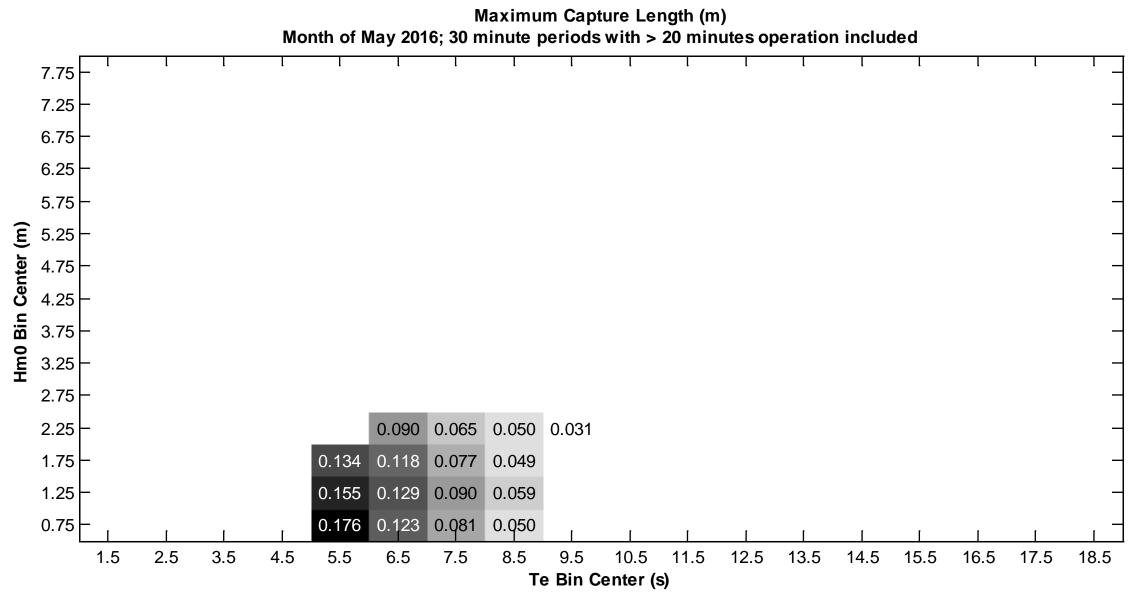




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Maximum capture length matrix





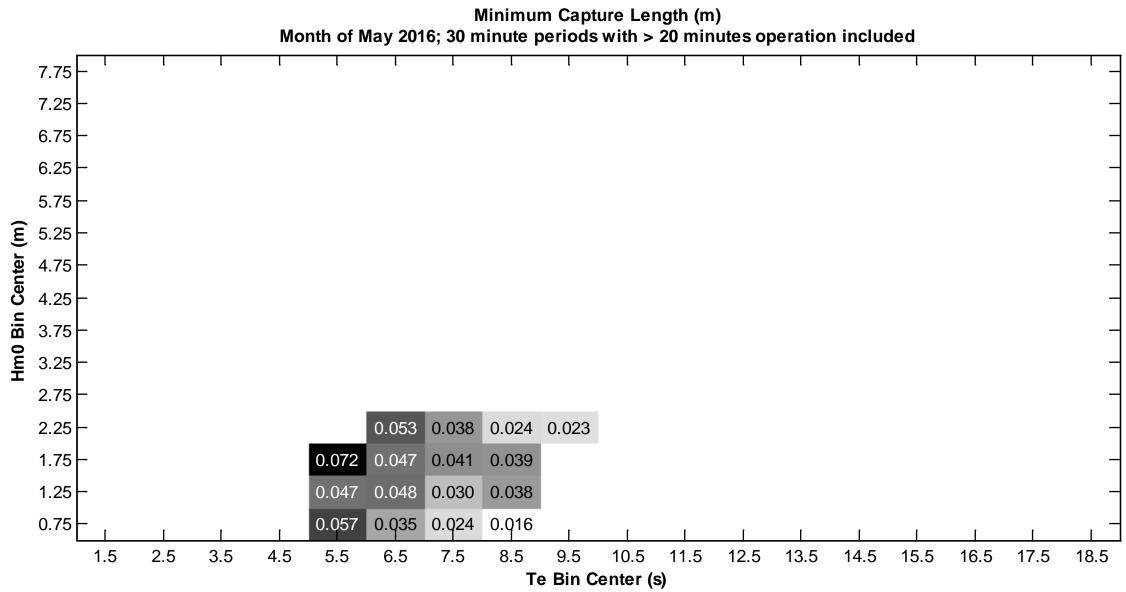
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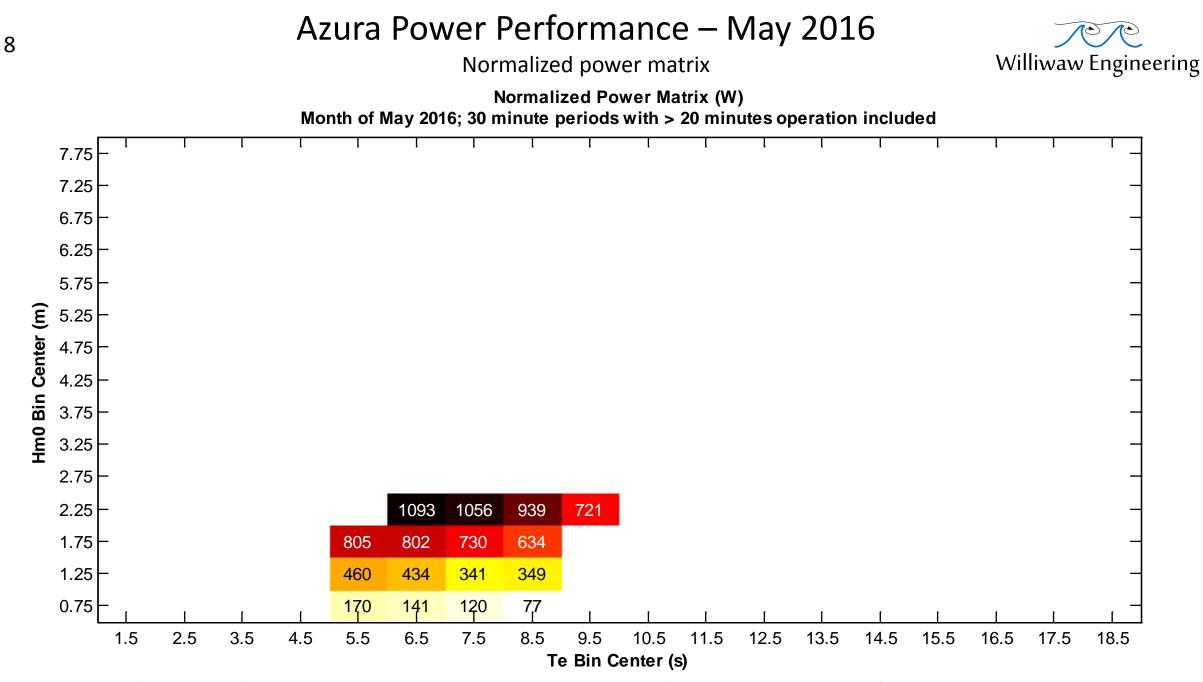
Azura Power Performance – May 2016

Minimum capture length matrix

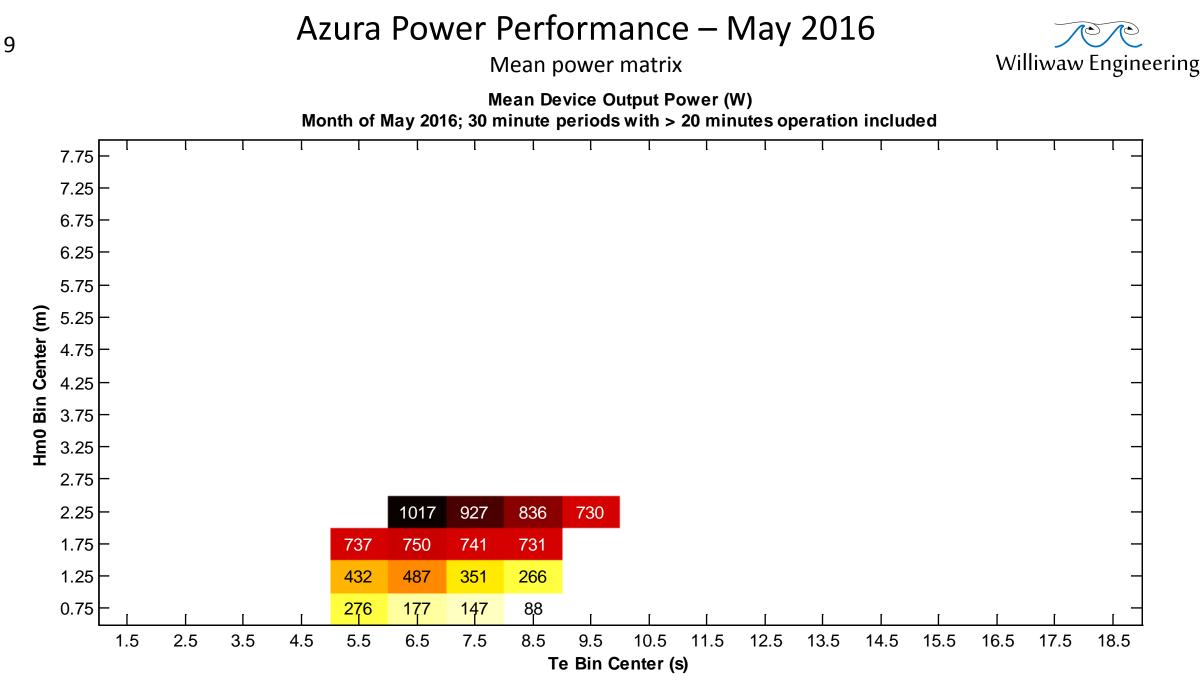




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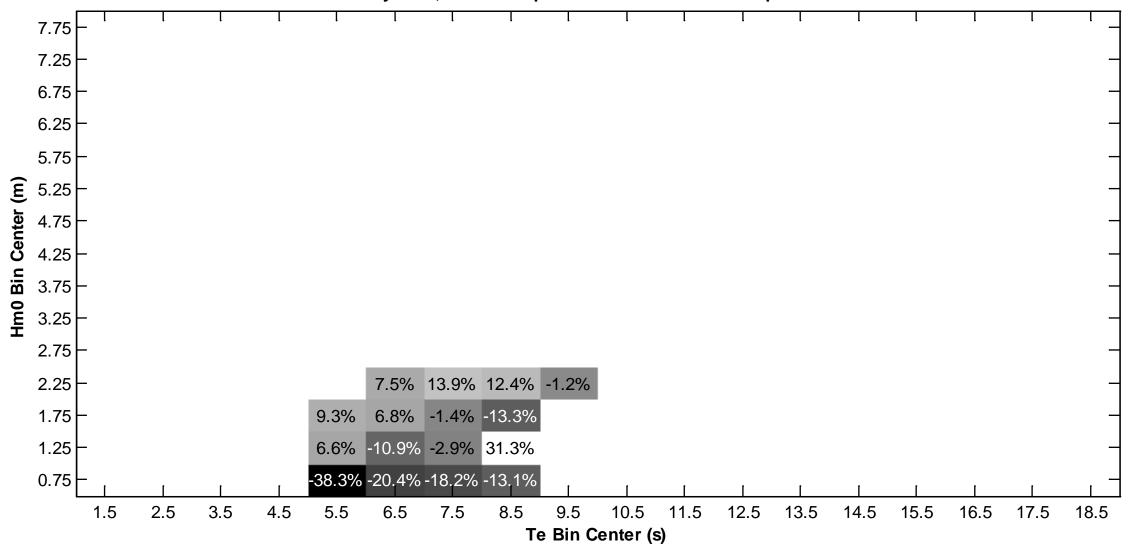


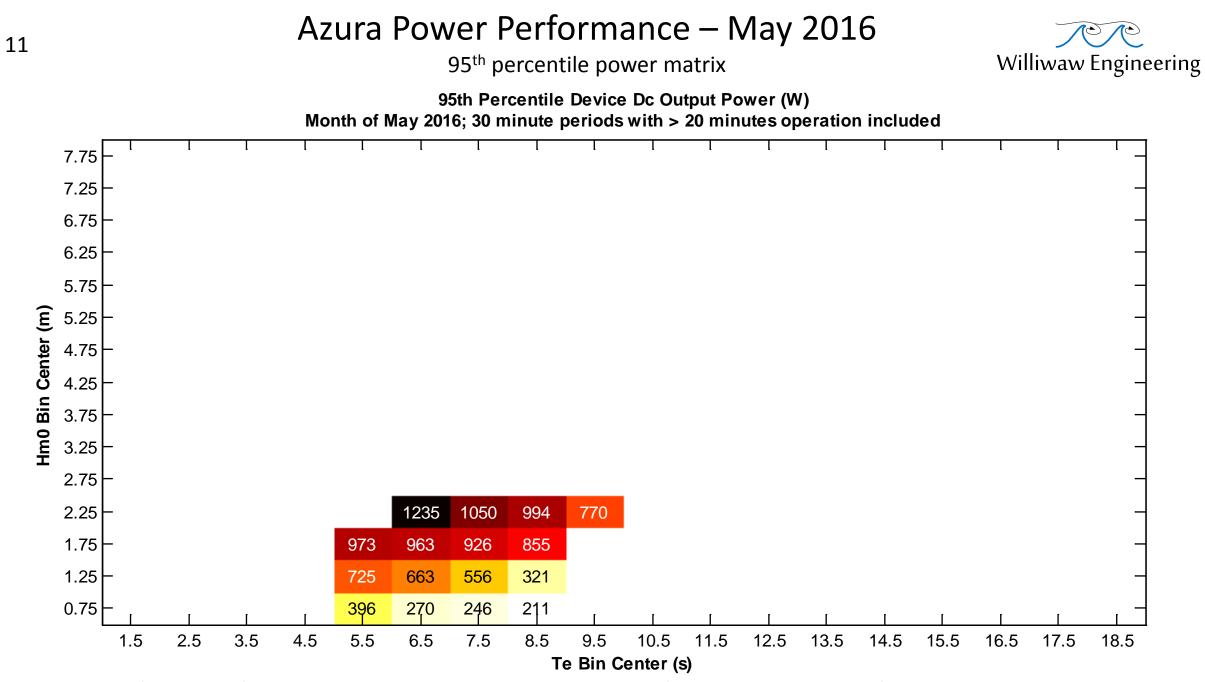
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Percent difference between normalized and mean power matrix



Percent difference between normalized and direct measured power matrices Month of May 2016; 30 minute periods with > 20 minutes operation included





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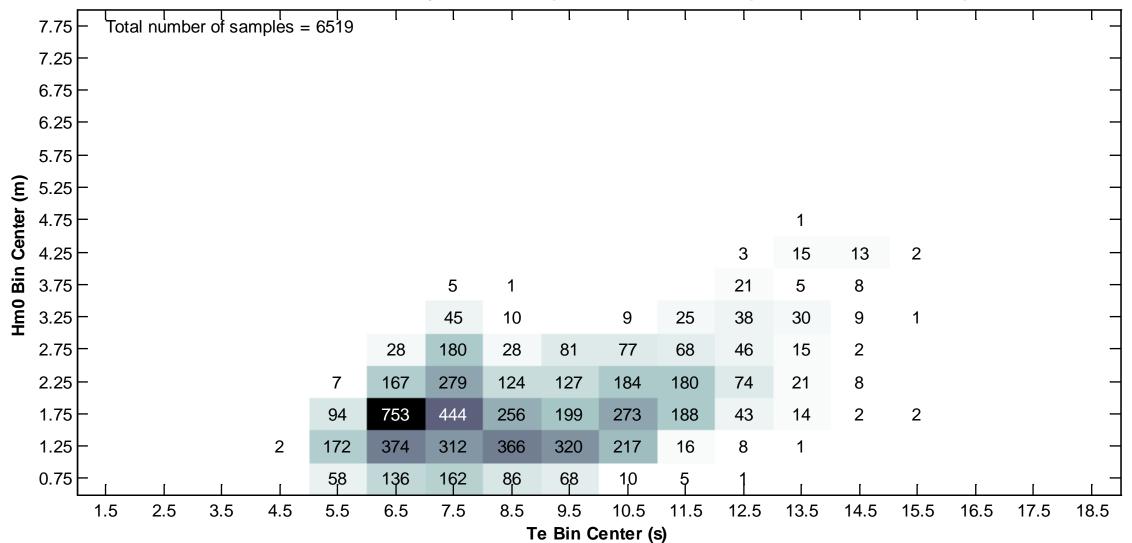
Azura Power Performance Cumulative Data January – May 2016

Data samples collected



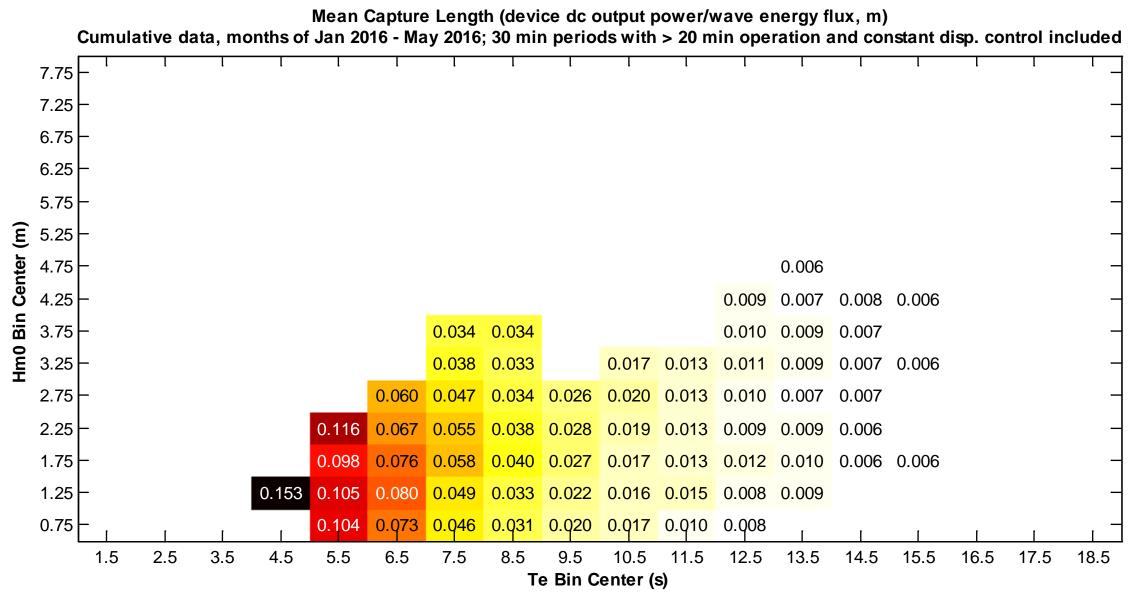
Sample Count (30 min sample periods)

Cumulative data, months of Jan 2016 - May 2016; 30 min periods with > 20 min operation and constant disp. control included



Mean capture length matrix





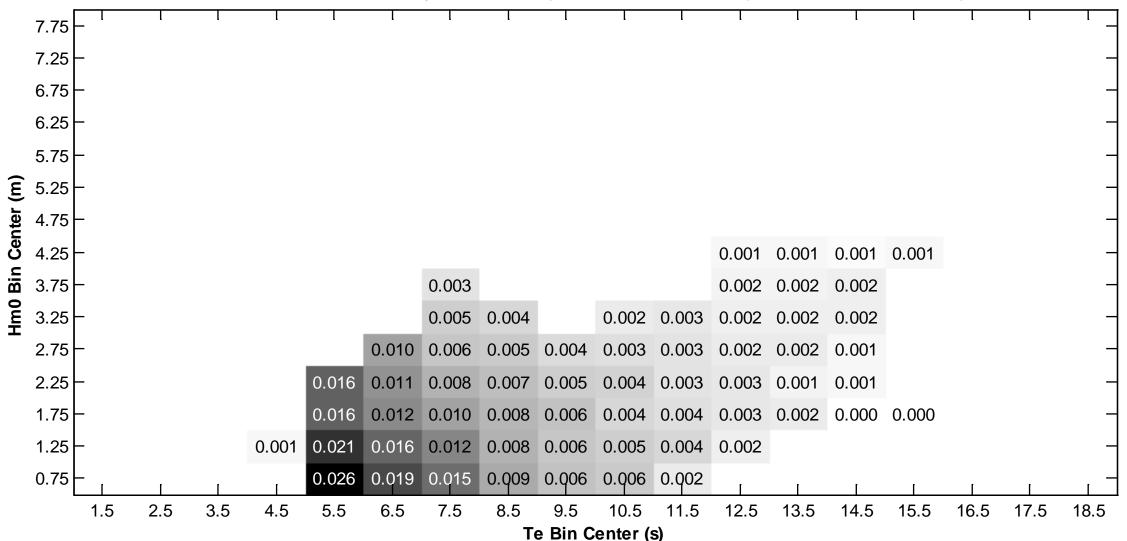
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Standard deviation of capture length



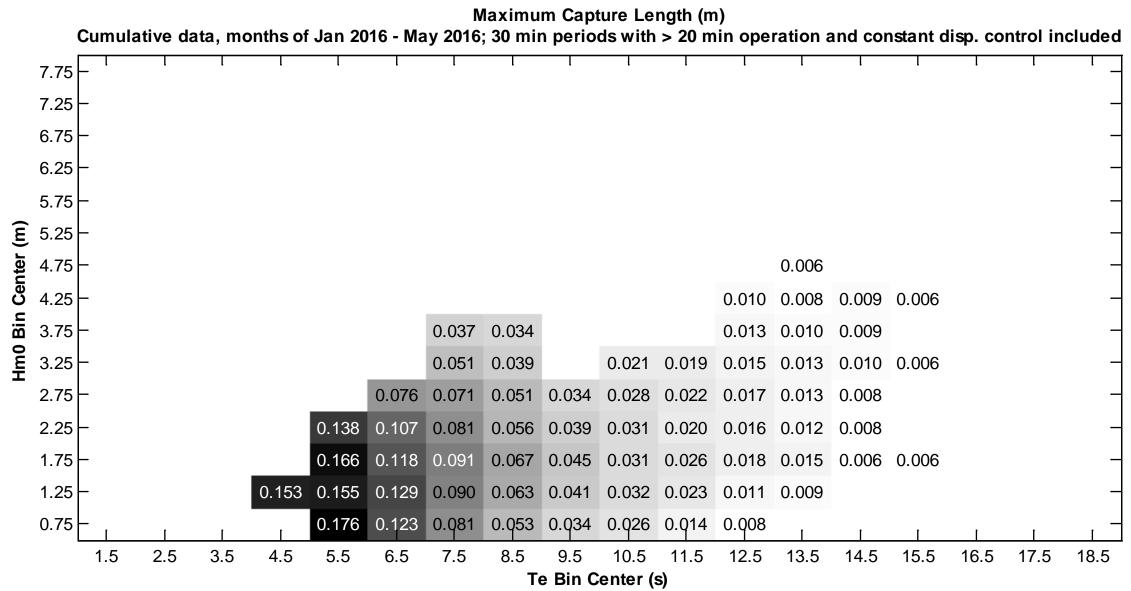
Standard Deviation of Capture Length (m)

Cumulative data, months of Jan 2016 - May 2016; 30 min periods with > 20 min operation and constant disp. control included



Maximum capture length matrix



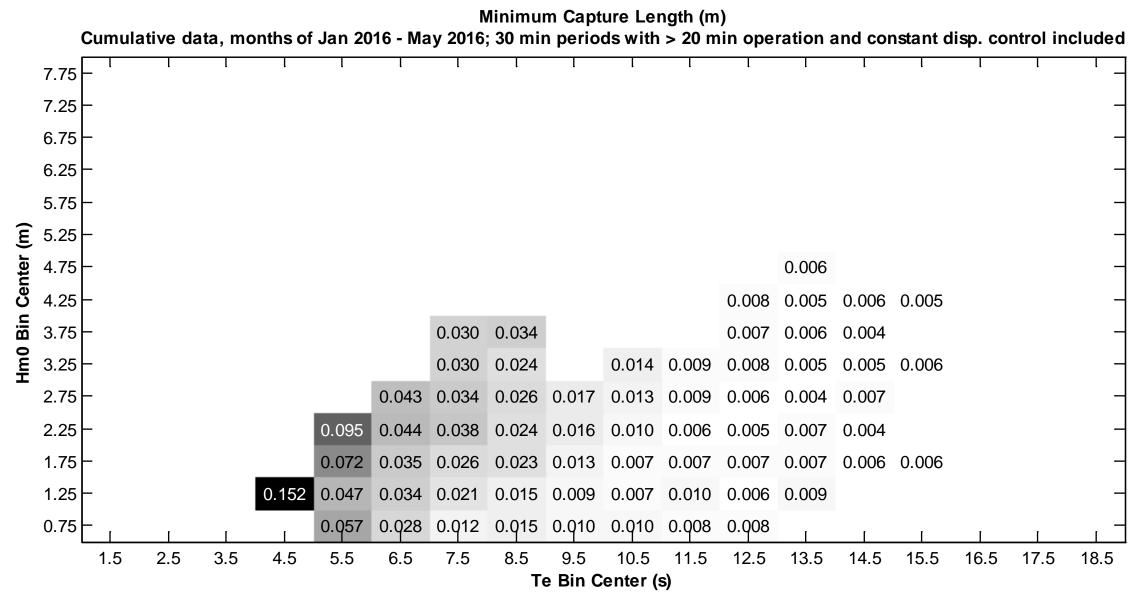


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Minimum capture length matrix

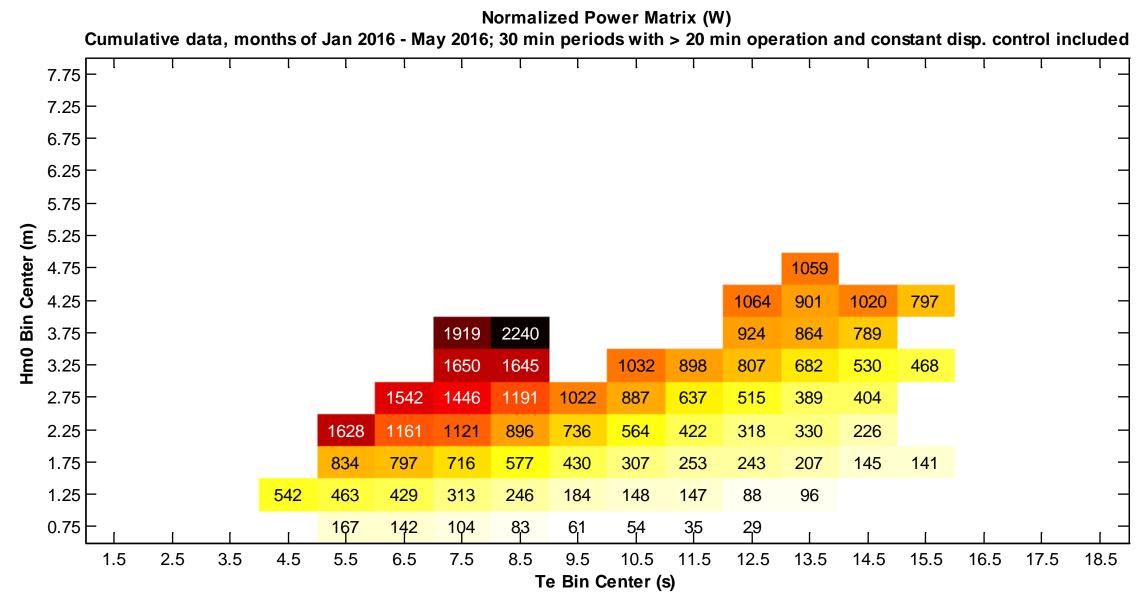




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Normalized power matrix

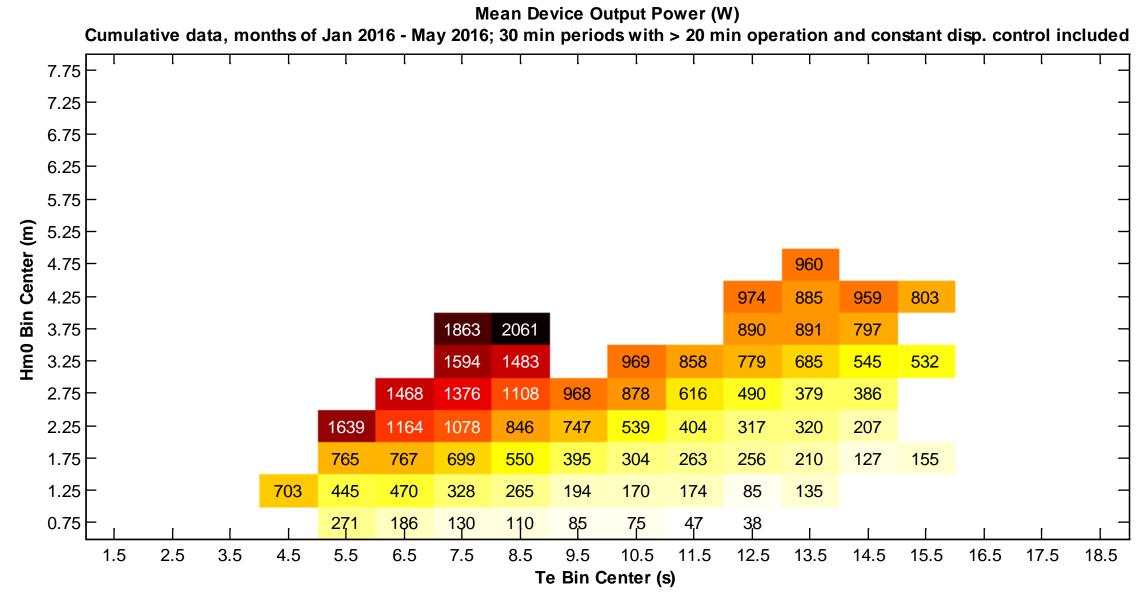




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Mean power matrix





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Percent difference between normalized and mean power matrix



Percent difference between normalized and direct measured power matrices Cumulative data, months of Jan 2016 - May 2016; 30 min periods with > 20 min operation and constant disp. control included 7.75 7.25 6.75 6.25 5.75 Hm0 Bin Center (m) 5.25 4.75 10.4% 4.25 1.8% 6.4% -0.8% 9.2% 3.75 3.8% -3.0% -1.1% 3.0% 8.7% 3.25 6.5% 4.6% 3.5% 10.9% 3.6% -0.5% -2.7% -12.1% 5.1% 2.75 5.0% 7.5% 5.5% 1.1% 3.4% 5.3% 2.6% 4.7% 2.25 -0.7% -0.2% 4.0% 5.9% -1.5% 4.7% 4.4% 0.6% 3.3% 9.2% 1.75 9.0% 4.0% 2.4% 4.9% 8.8% 0.9% -3.7% -5.1% -1.1% 13.8% -8.9% 1.25 -22.8% 4.0% -8.8% -4.7% -7.1% -5.3% -13.1% -15.4% 3.3% -28.7% 0.75 -38.4% -23.7% -19.8% -24.8% -28.0% -27.8% -25.3% -24.0% 2.5 3.5 17.5 18.5 1.5 4.5 5.5 6.5 7.5 8.5 9.5 10.5 11.5 12.5 13.5 14.5 15.5 16.5 Te Bin Center (s)

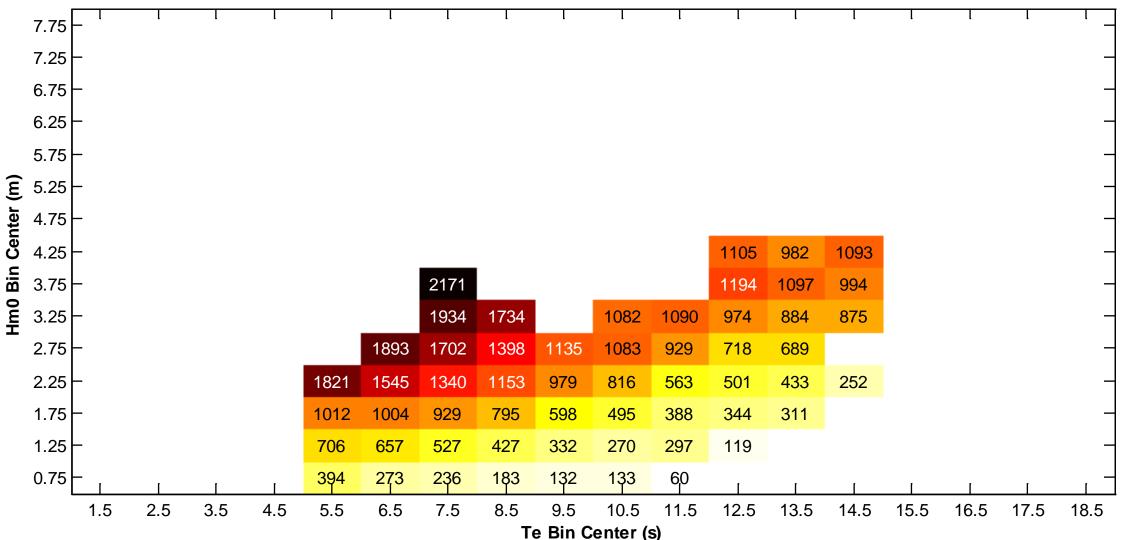
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95th percentile power matrix





Cumulative data, months of Jan 2016 - May 2016; 30 min periods with > 20 min operation and constant disp. control included



Attachment 2

Azura 30 minute average float angle data plots

Azura 30 minute average float angle data – May 2016

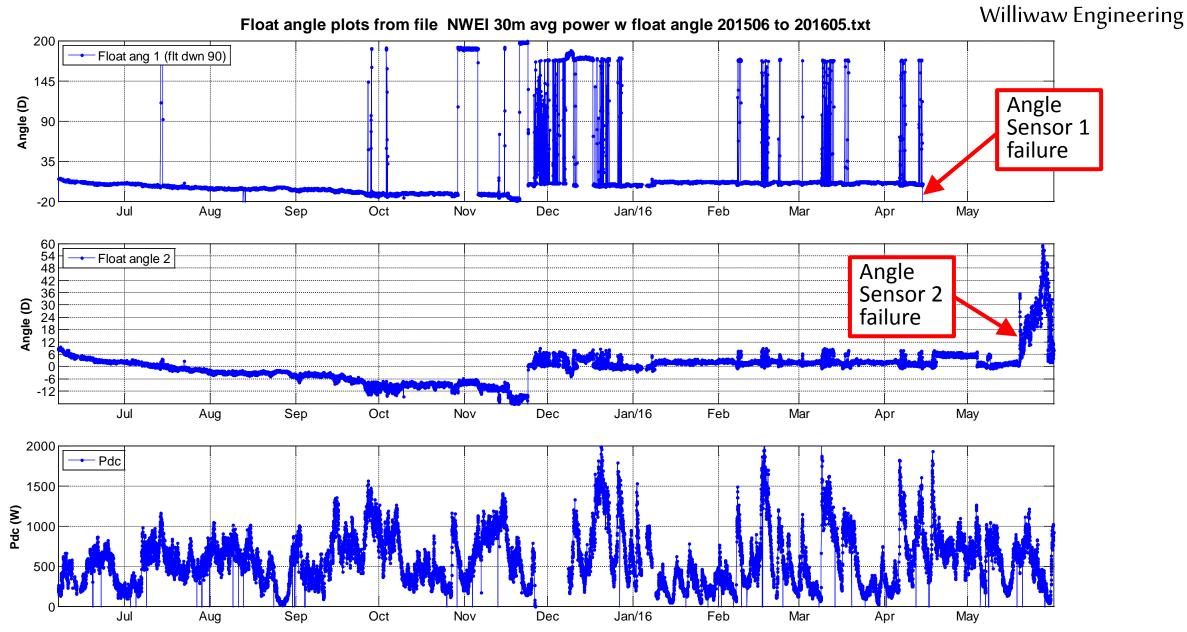


Summary

- See Slide 2 for plot of June 2015 May 2016 data
- Angle sensor 2 failed in mid-May 2016 and has had a large zero drift since then. Videos of the device confirm that the average float angle readings during the second half of May have been incorrect.
- Angle data before mid-May indicates that the device ballasting has been near ideal and steady since Dec 2015.
- Angle sensor 1 failed a month earlier, on April 14.

Azura 30 min average float angle data through May 2016

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Attachment 3

Azura cRIO enclosure and drybox humidity plots

Azura cRIO enclosure and drybox humidity May 2016 Williwaw Engineering

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